

TSTE25 Power Electronics

Lecture 4

Tomas Jonsson

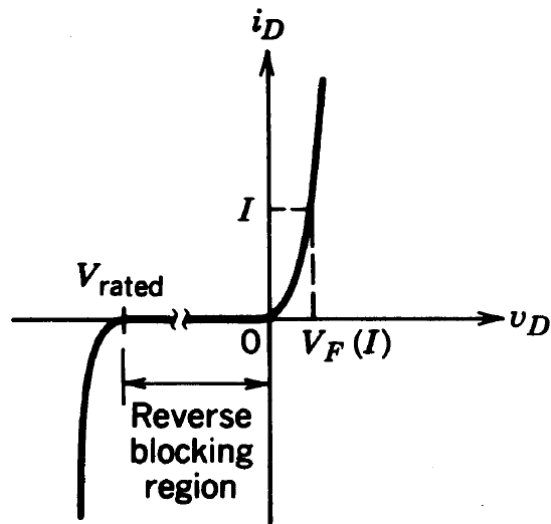
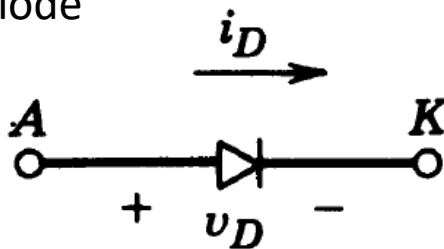
ISY/EKS

Outline

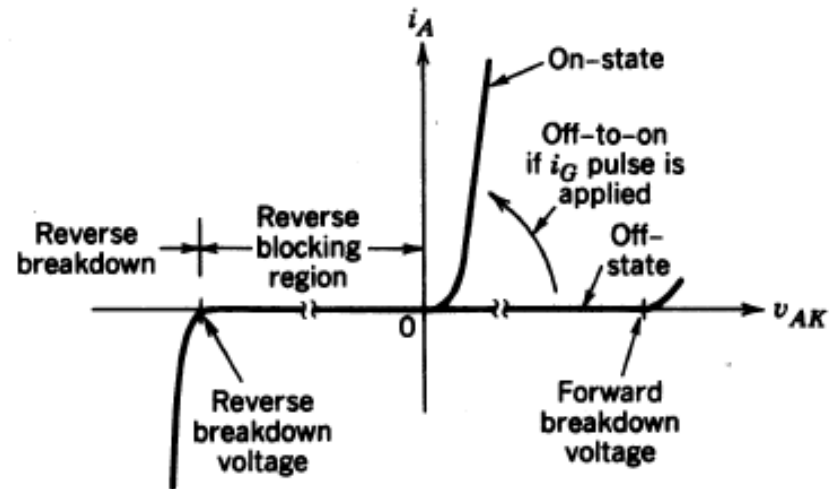
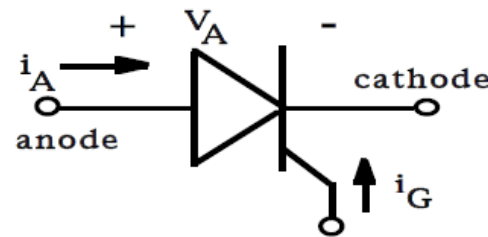
- Semiconductor switches
- Loss calculation
- Switching equivalents
- Thermal aspects

Semiconductors without turn-off capability

Diode

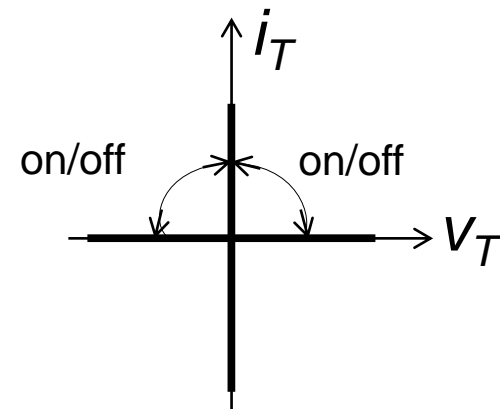
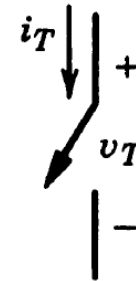


Thyristor circuit symbol.



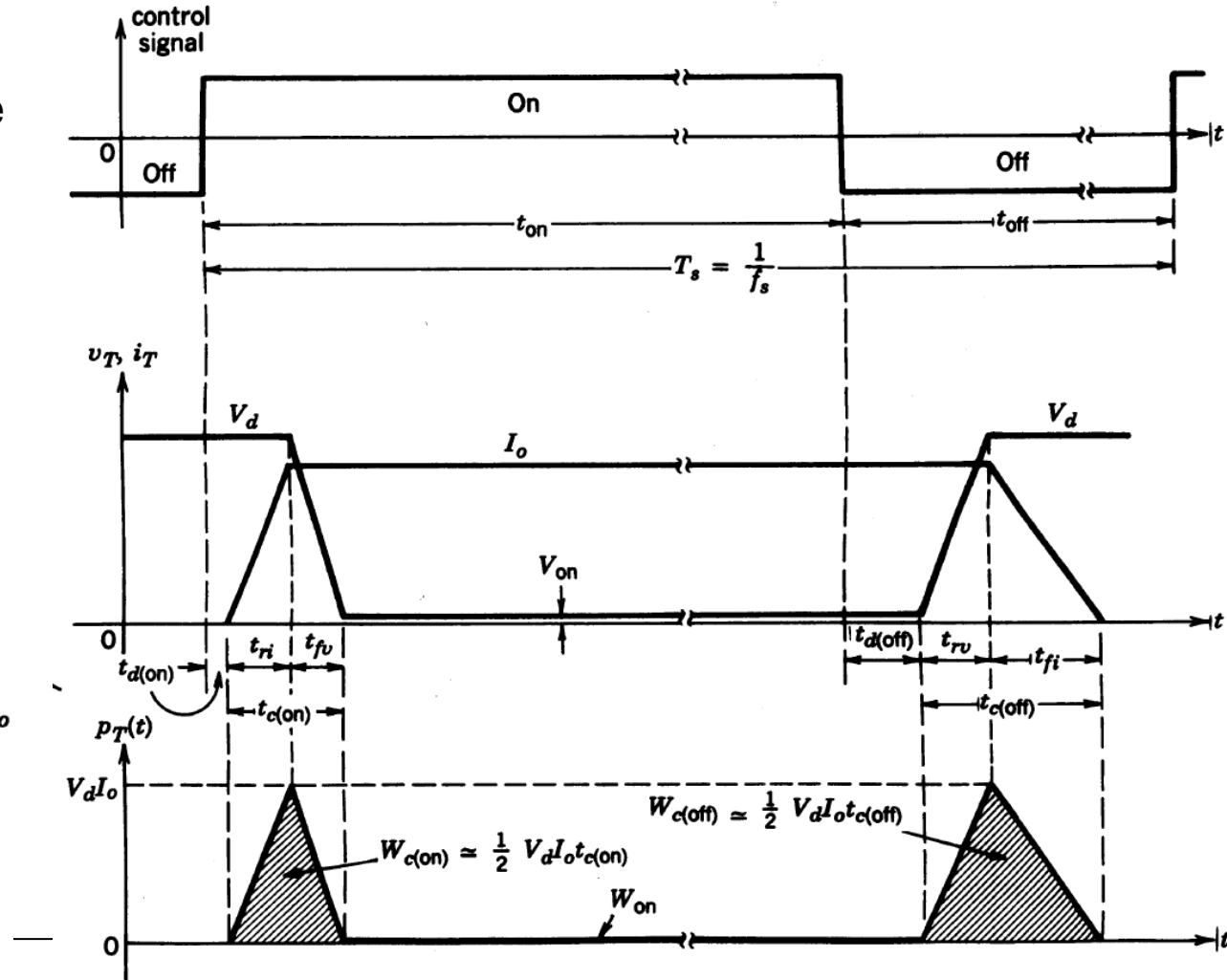
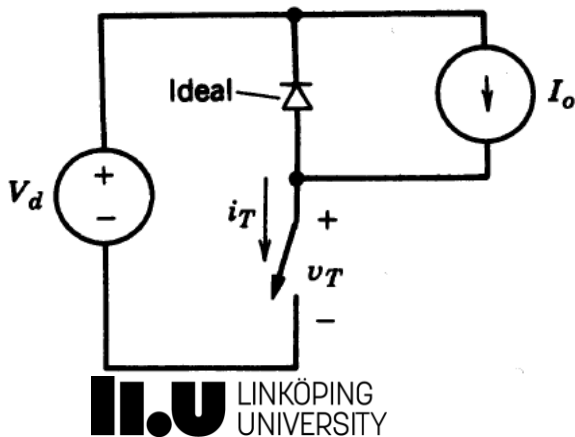
Ideal switch

- Accept voltages of both polarities
 - Both negative and positive
- Controlled turn-on and turn-off
- Conduct current in both directions
- No breakdown voltage
 - Perfect isolation in off state
- Zero on-resistance
 - No voltage drop over the switch
- No switch delay
- Zero energy switching
 - No power dissipated during operation



Non-ideal switch example

- Linear model
 - Rise and fall time on both V and I
 - Voltage drop V_{on}
 - I_o models an inductor
- Power loss!



DC/DC converter losses

Conduction losses

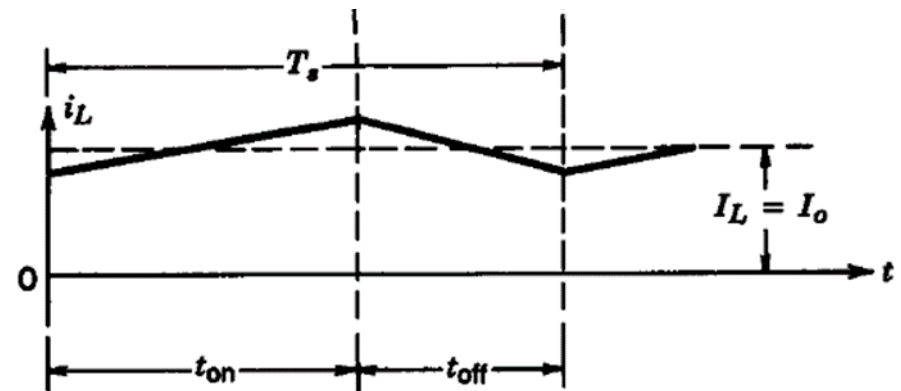
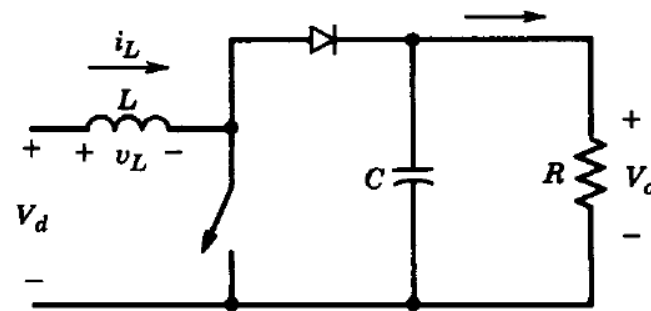
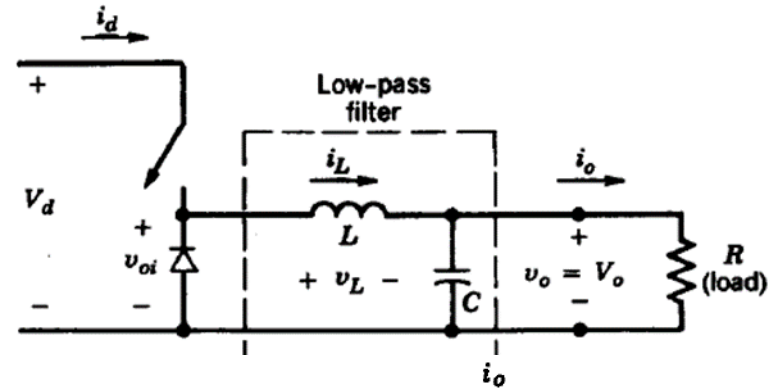
- $$P_{on} = r_{ds(on)} I_{sw,rms}^2 =$$

$$= D \cdot r_{ds(on)} I_{L,av}^2$$

Switching losses (average)

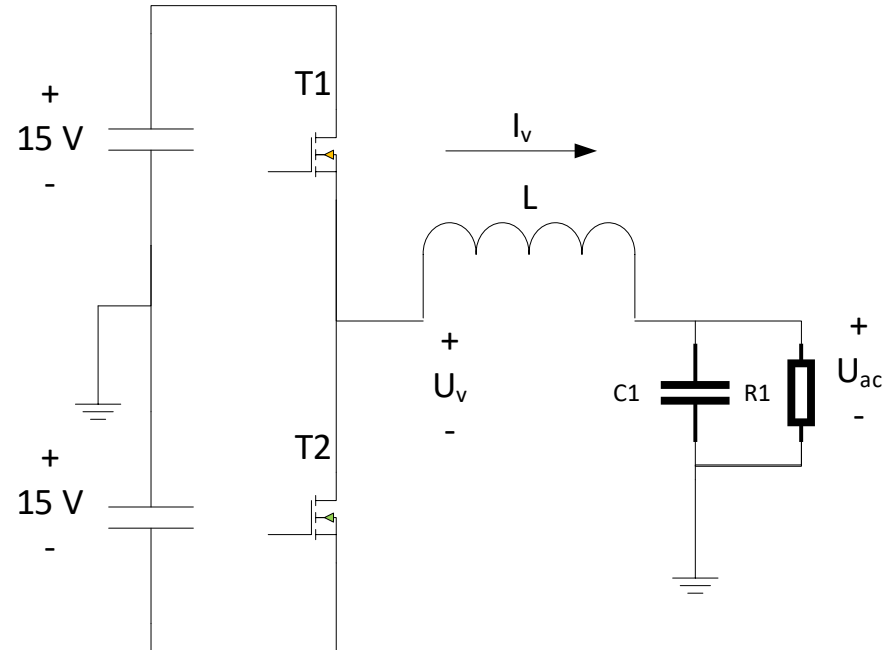
- $$P_s = \frac{1}{2} V_d I_{sw,av} f_s (t_{c(on)} + t_{c(off)})$$
- $$I_{sw,av} = I_{L,av}$$

- Further reading see document “Losses” in Lisam/Tutorials



Half-bridge converter example

- Total dc-voltage, positive-to-negative side
 - $U_d = 30V$
- DC-voltage positive and negative side to ground
 - $\frac{U_d}{2} = \pm 15V$



DC/AC converter losses

Conduction losses (Both switches)

- $$P_{on} = 2 \cdot r_{ds(on)} I_{sw,rms}^2 =$$

$$= 2D \cdot r_{ds(on)} I_{L,av}^2 =$$

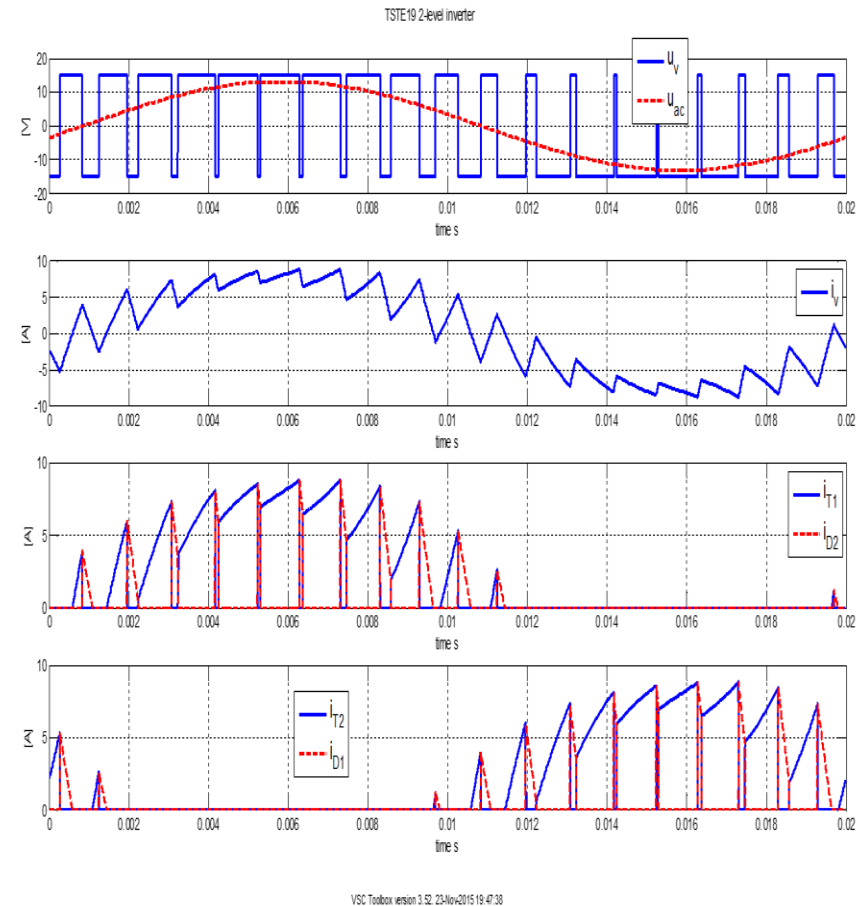
$$= \{D_{av} = 0.5\} = r_{ds(on)} I_{L,av}^2$$

Switching losses (total average for both switches in a half-bridge)

- $$P_s = \frac{1}{2} V_d I_{sw,av} f_s (t_{c(on)} + t_{c(off)})$$
- $$I_{sw,av} = \frac{2\sqrt{2}}{\pi} I_{v,rms} = 0.9 I_{v,rms}$$

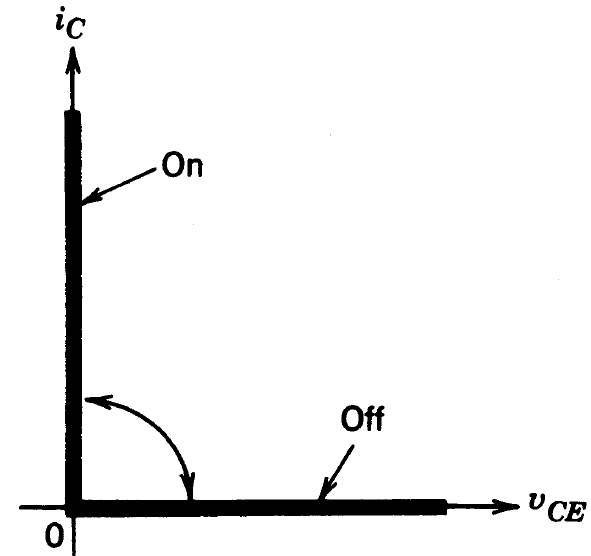
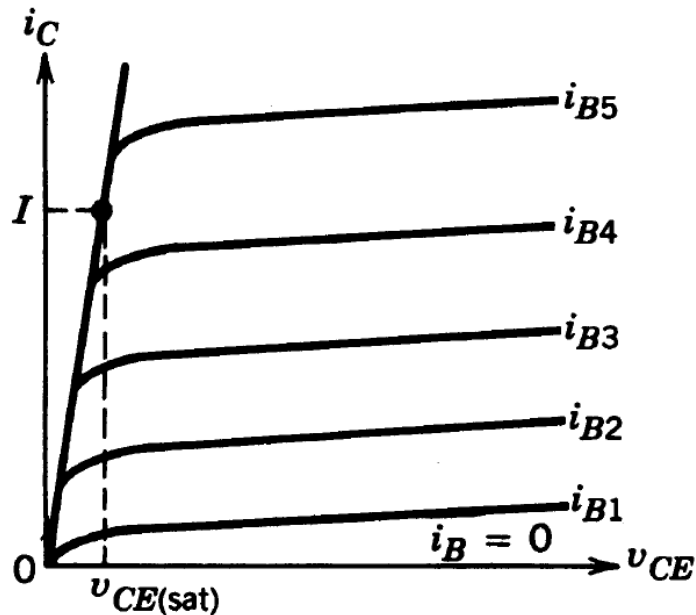
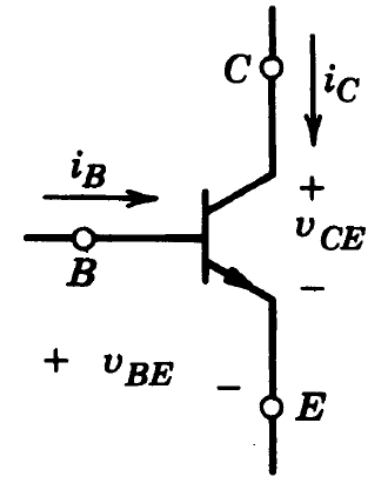
(based on full-wave pulses)

- Further reading see document “Losses” in Lisam/Tutorials



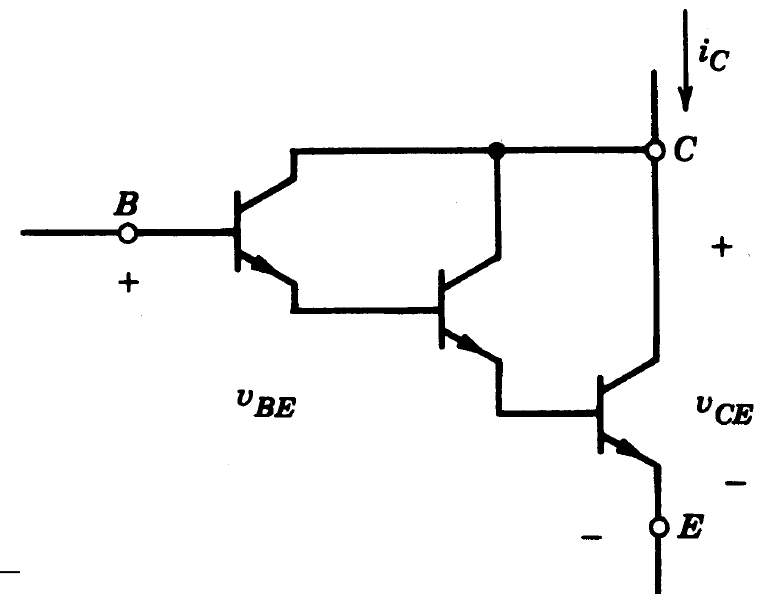
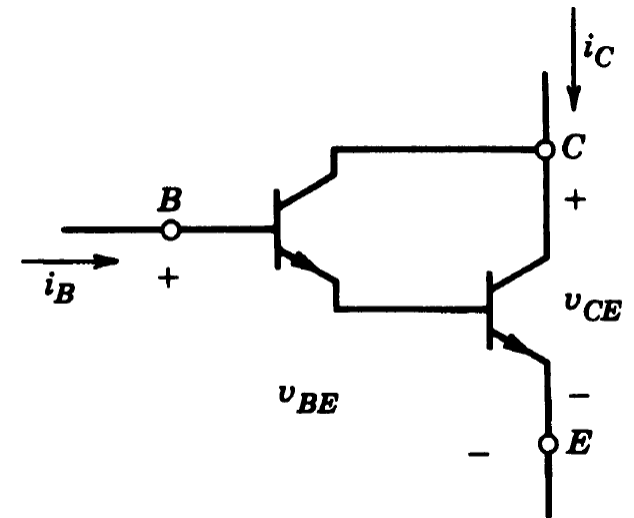
Bipolar junction transistors (BJT)

- Current controlled by base current i_B
- $5 < h_{FE} = \frac{I_C}{I_B} < 10$ for power BJT
- Possible to turn on and off



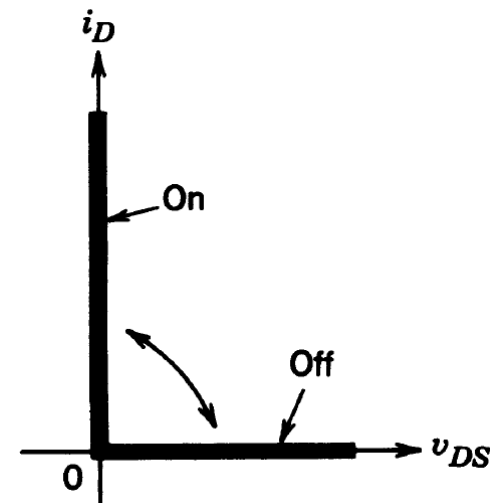
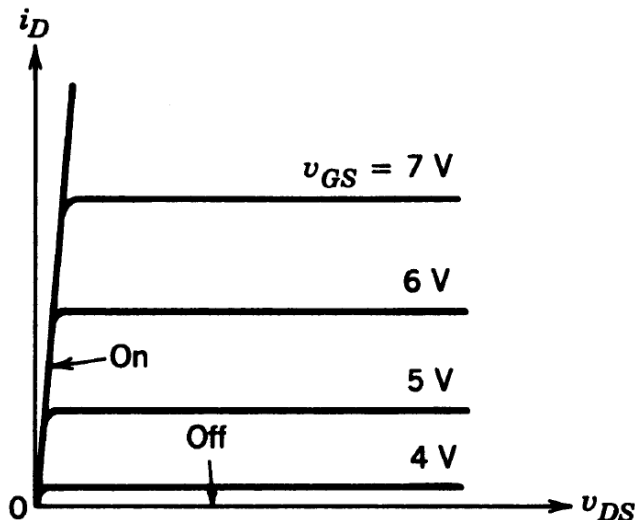
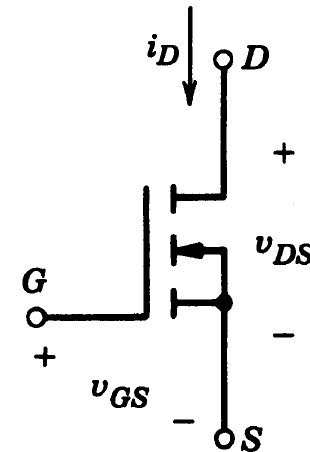
Darlington bipolar transistors

- Increase h_{FE}
- Increases also v_{CEsat} . Higher losses!
- $0.1 \text{ us} < \text{switching time} < 10 \text{ us}$
- Integrated on a single silicon chip

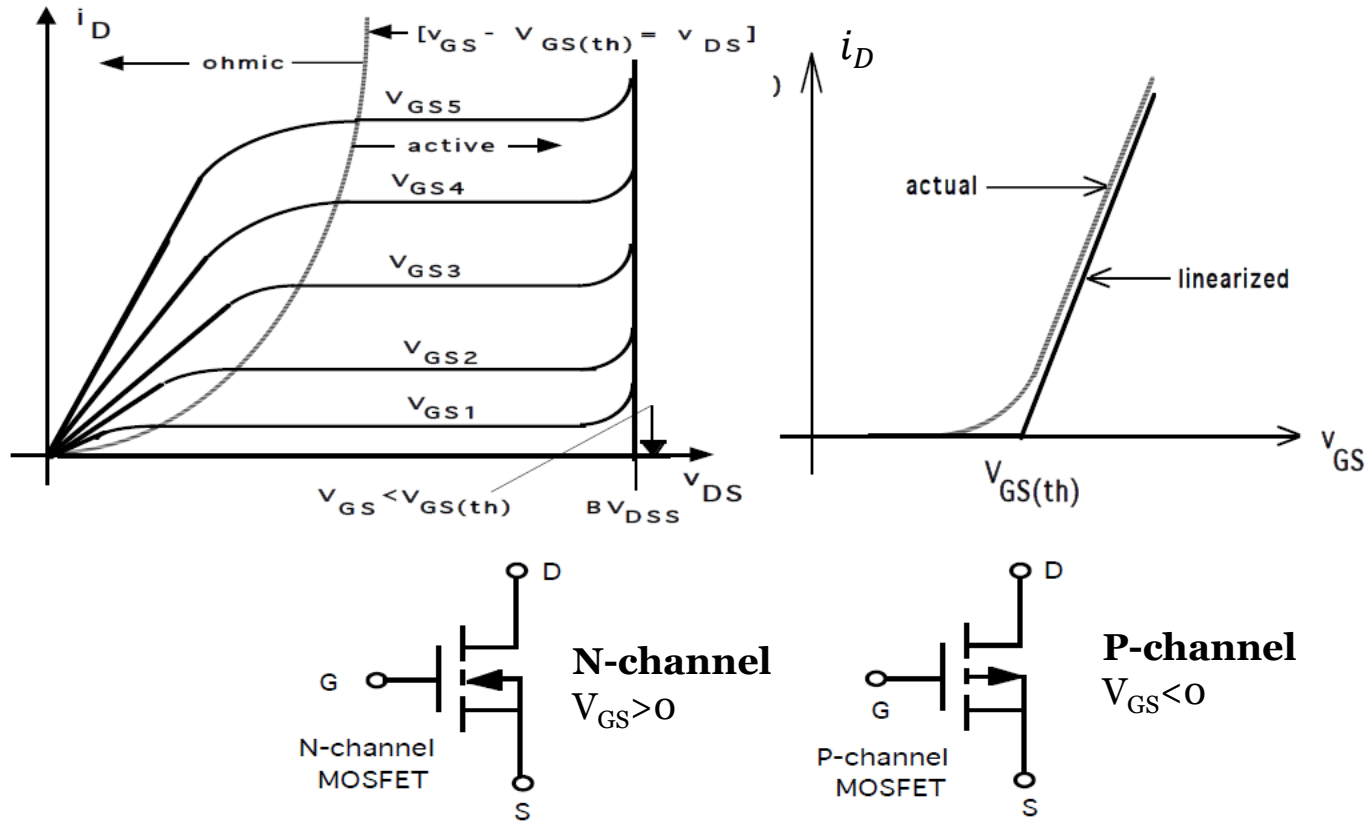


MOSFET transistors

- Voltage controlled, $V_{GS} > V_{GS(th)}$
- Fast switching
 - $10 \text{ ns} < t < 500 \text{ ns}$
- Tradeoff R_{on} vs Blocking voltage
- Bidirectional current conduction
- Built in “body” diode



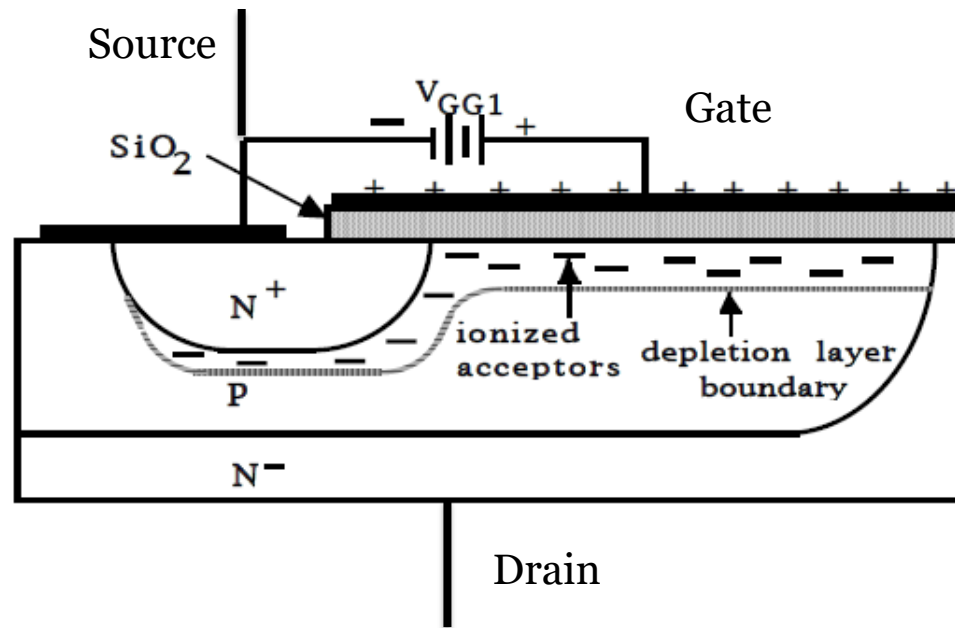
MOSFET I-V Characteristics and Circuit Symbols



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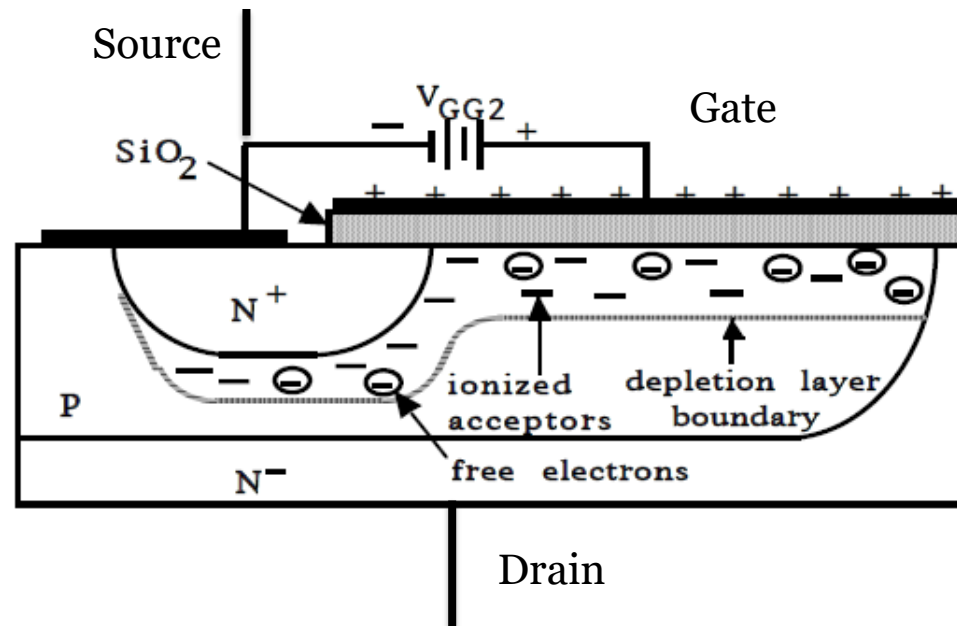
MOSFET channel conduction control

- Low gate voltage
 - $V_{GS} \ll V_{GS(th)}$
- Inversion layer isolating drain N^- from source N^+



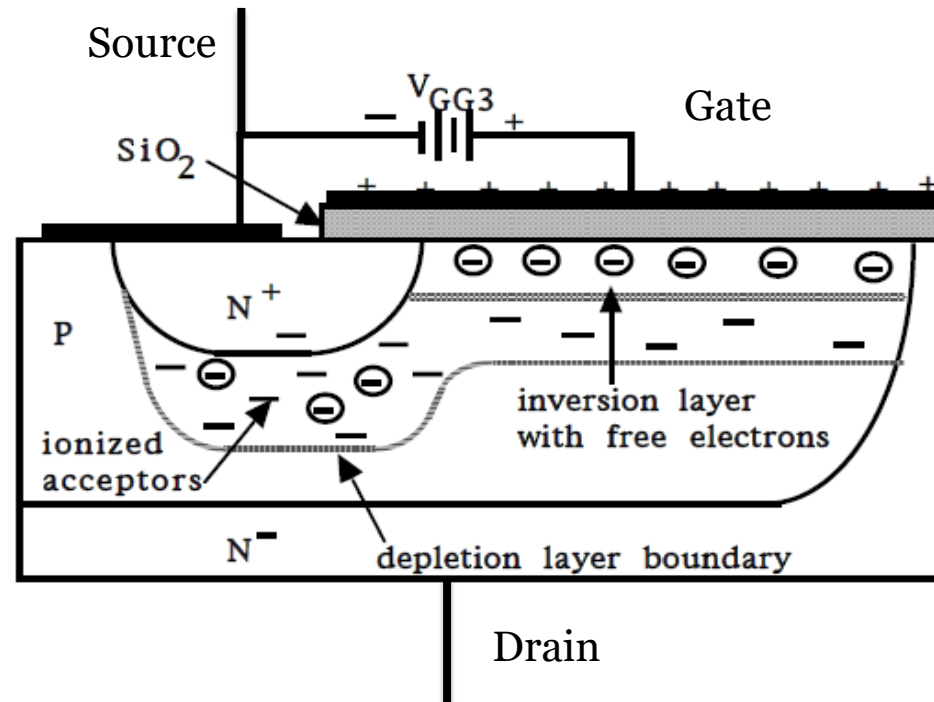
MOSFET channel conduction control

- Increasing gate voltage but below threshold
 - $V_{GS} < V_{GS(th)}$
- Inversion layer with some free electrons still isolating drain N^- from source N^+



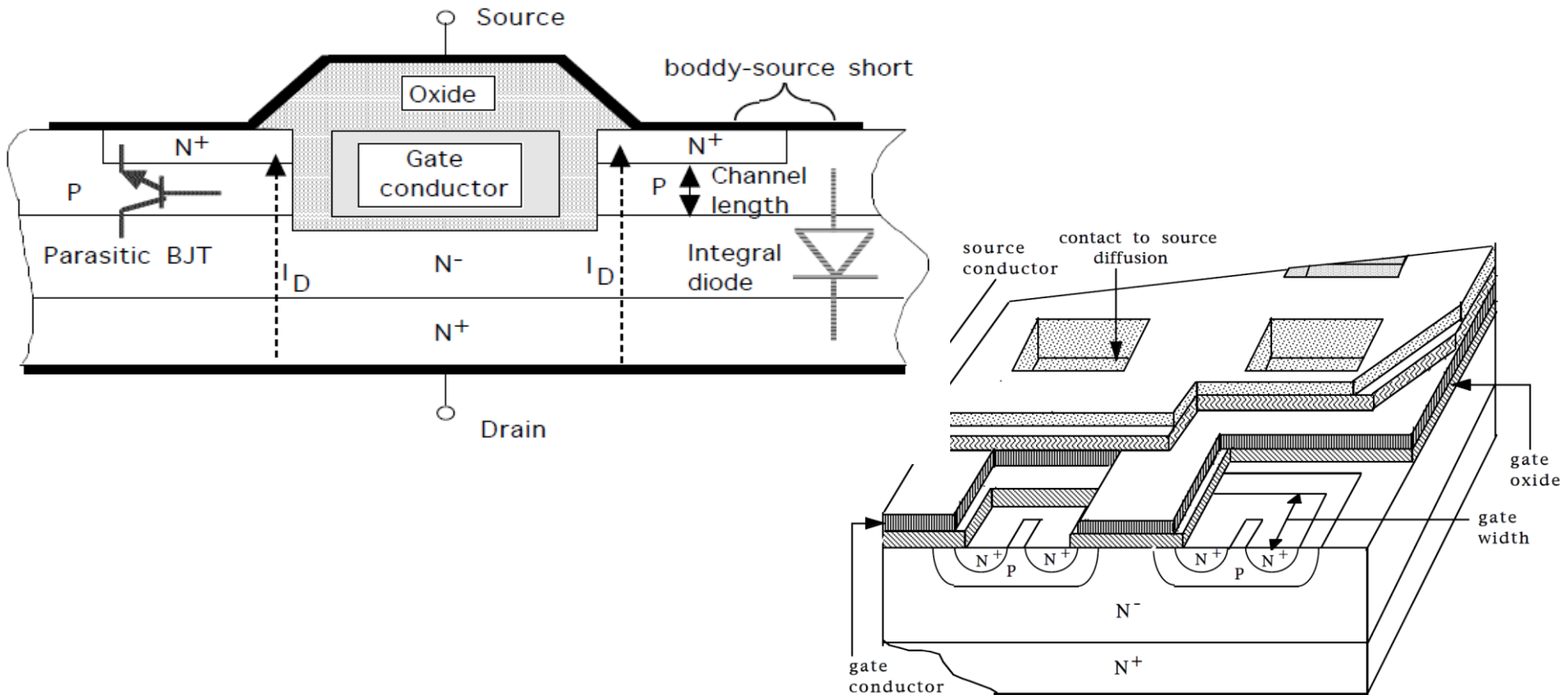
MOSFET channel conduction control

- High gate voltage above threshold
- $V_{GS} > V_{GS(th)}$
- Conductive channel of free electrons formed between drain N^- and source N^+



MOSFET implementation

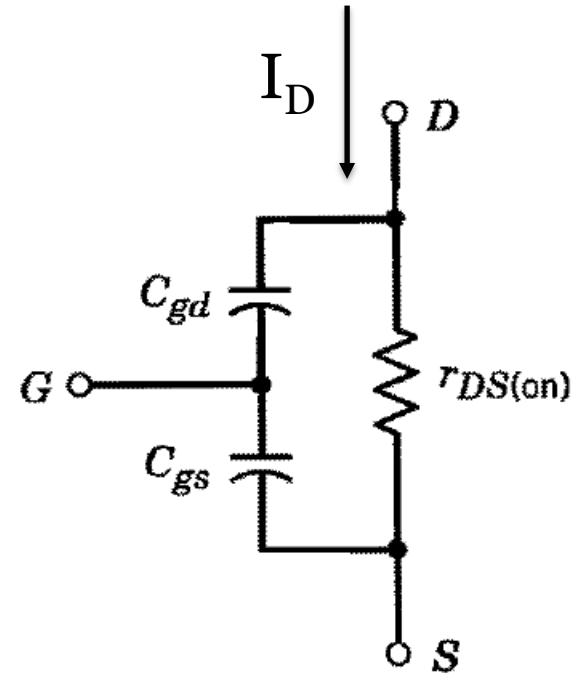
- Thousands of cells in parallel



MOSFET on-state equivalent

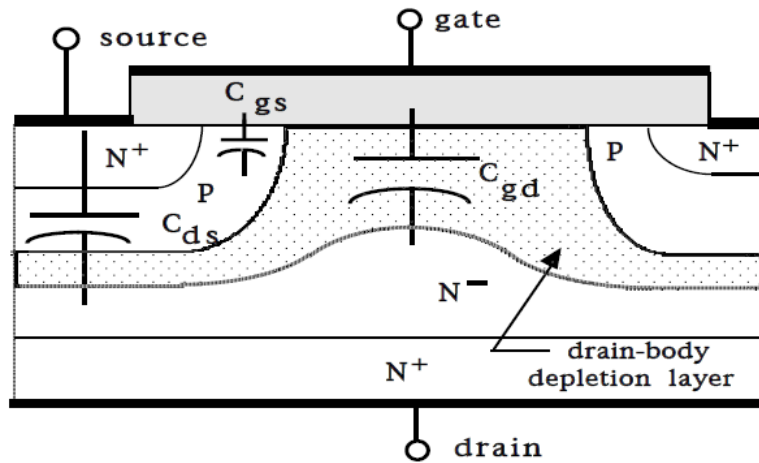
- On-state conduction losses

$$P_{on} = r_{DS(on)} I_D^2$$

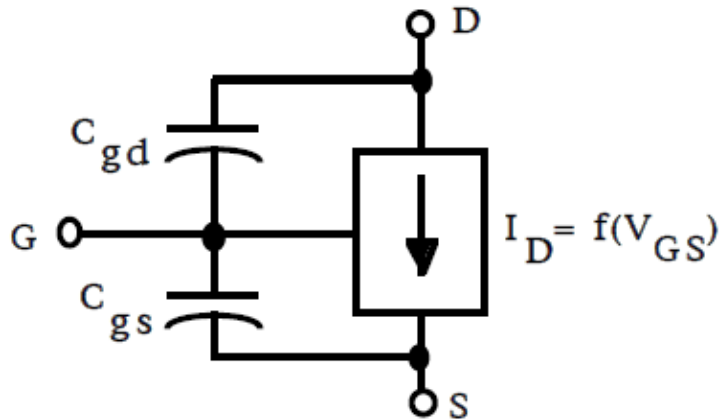
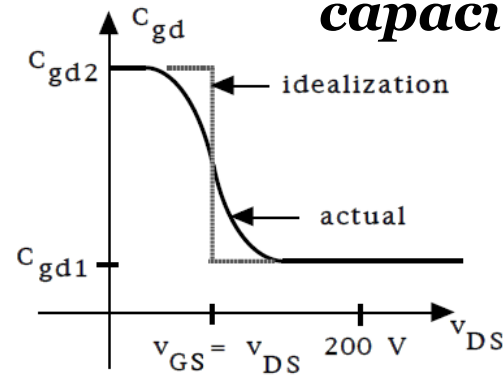


MOSFET equivalent circuit
for on-state operation

MOSFET turn-on/turn-off equivalent



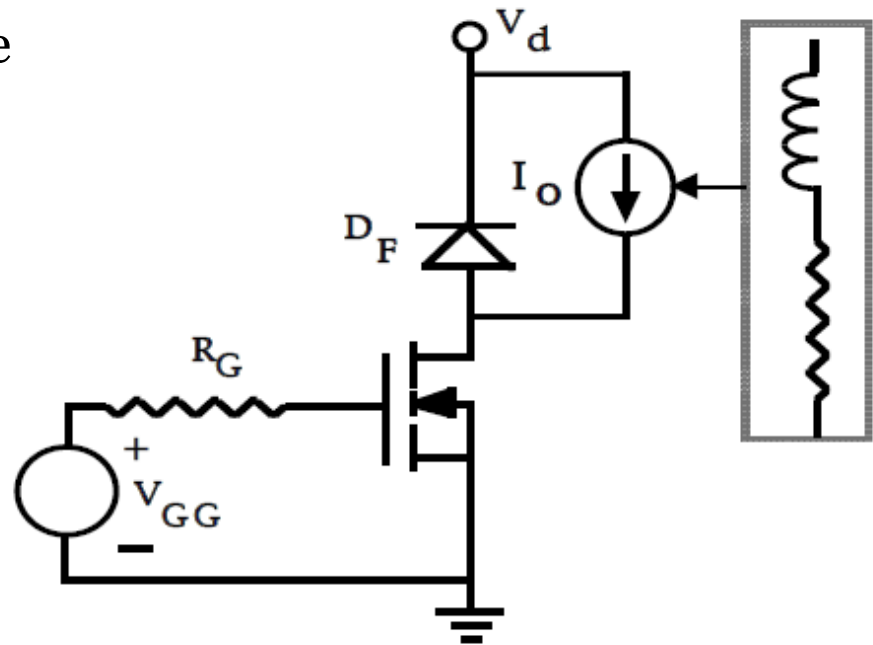
C_{gd}: "Miller capacitance"



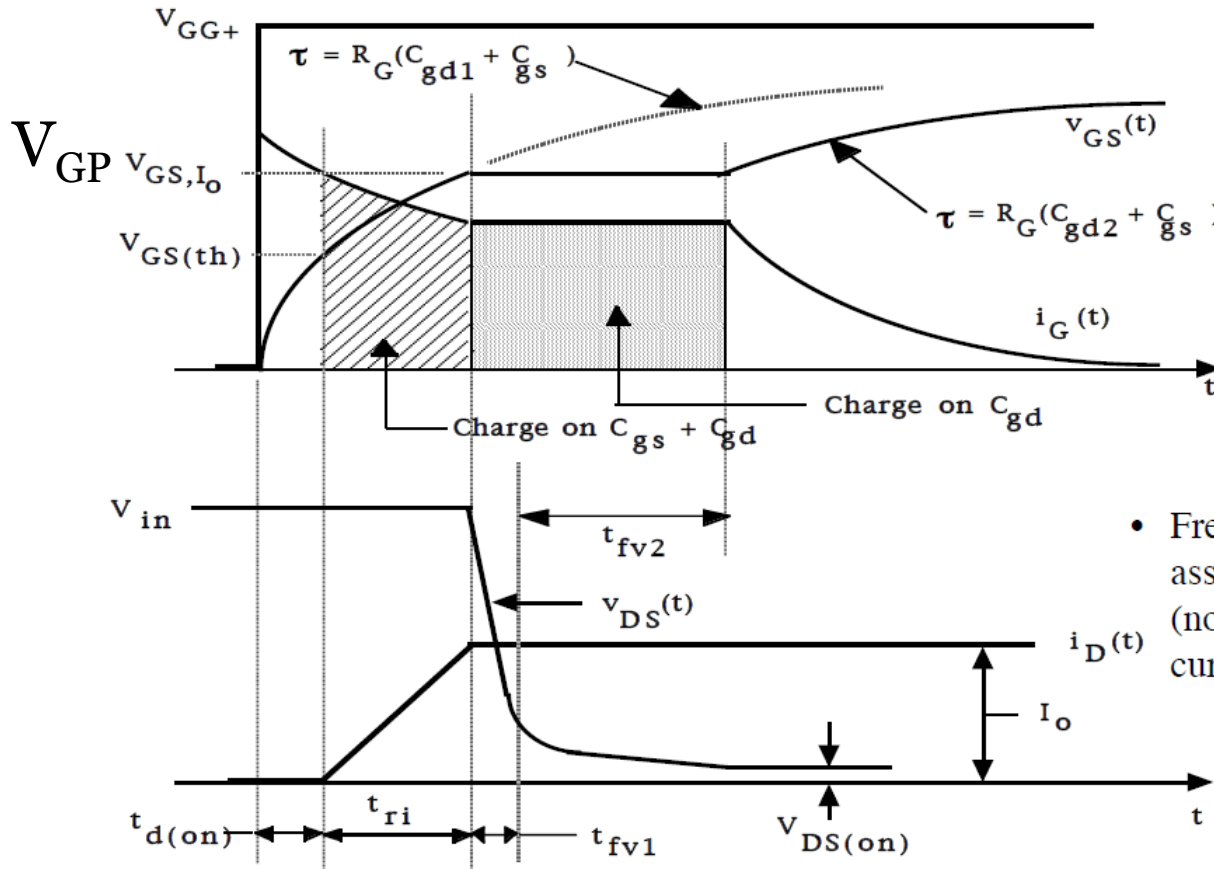
MOSFET equivalent circuit for off-state and active region operation

Switching MOSFET – Diode pair

- The current I_o is either conducted through the diode (when MOSFET is off) or through the MOSFET
- Turn-on: $V_{GG} \gg V_{GS(th)}$
- Turn-off: $V_{GG} = 0$



MOSFET-based Buck Converter Turn-on Waveforms

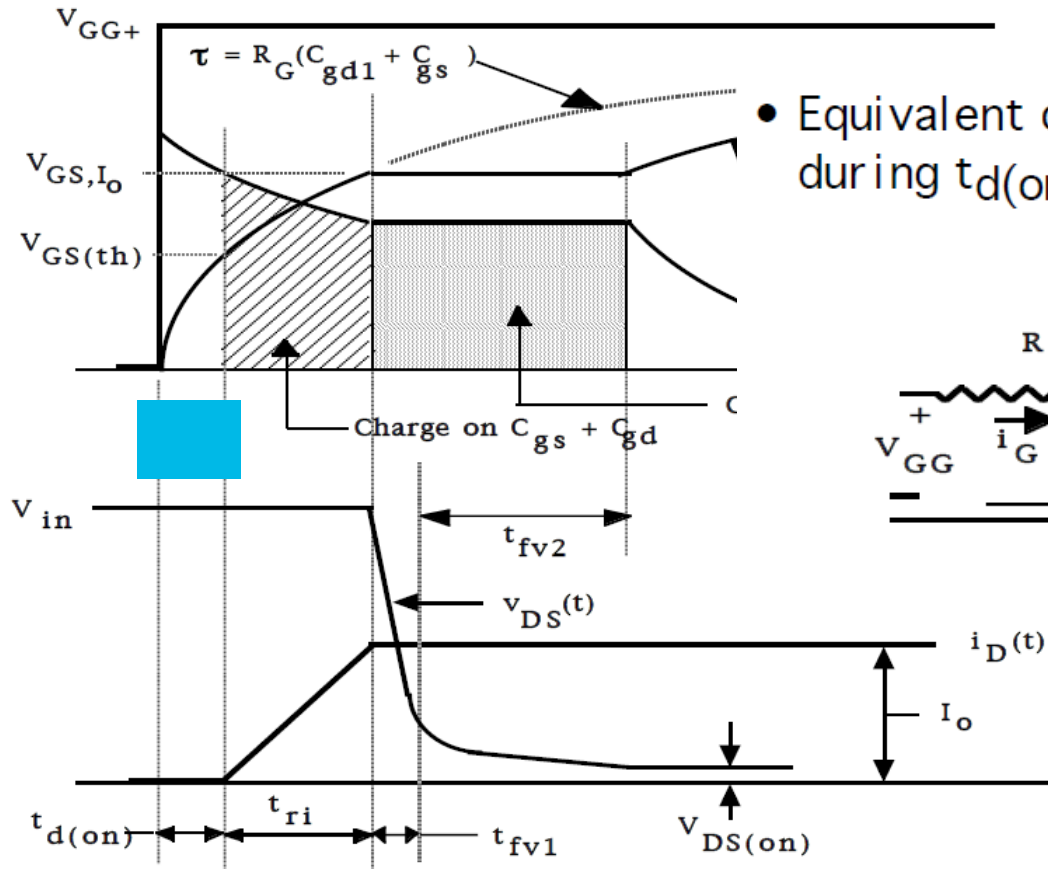


“Miller plateau”

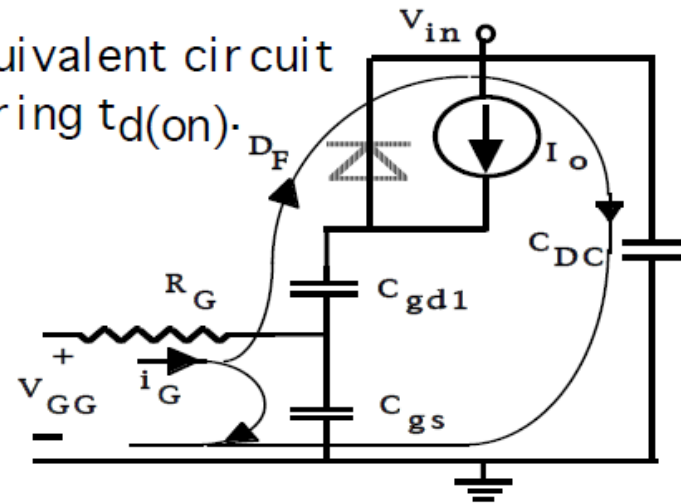
- Free-wheeling diode assumed to be ideal. (no reverse recovery current).

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MOSFET-based Buck Converter Turn-on Waveforms



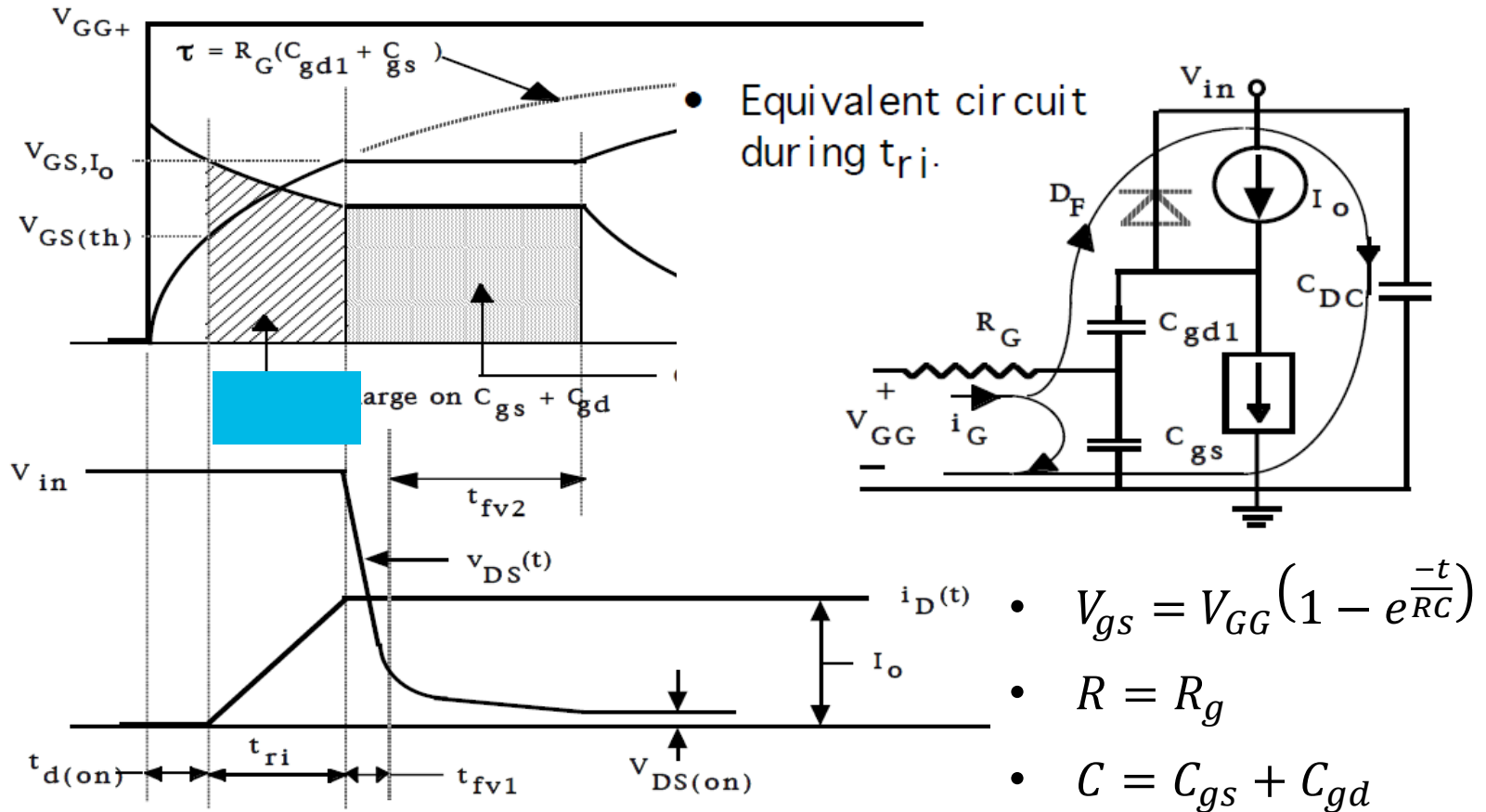
• Equivalent circuit during $t_{d(on)}$:



- $V_{gs} = V_{GG} \left(1 - e^{-\frac{t}{RC}}\right)$
- $R = R_g$
- $C = C_{gs} + C_{gd}$

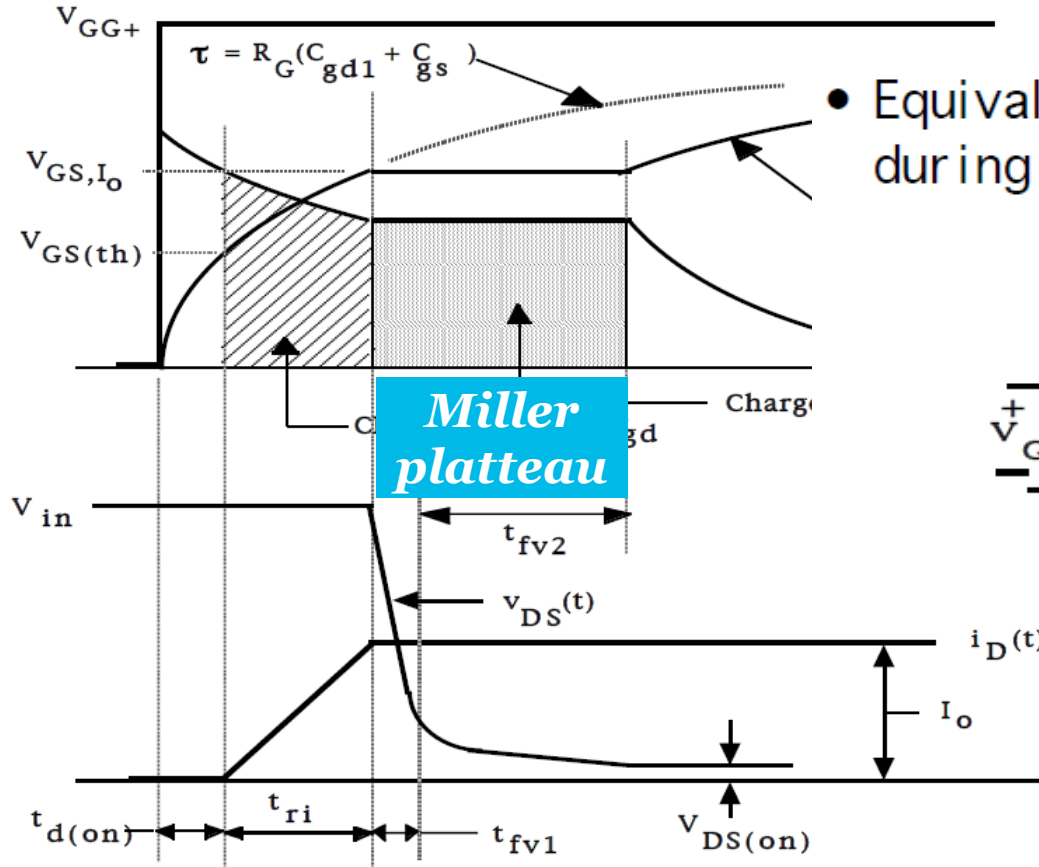
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MOSFET-based Buck Converter Turn-on Waveforms

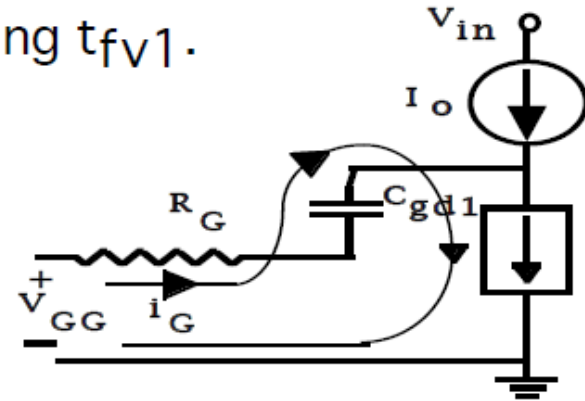


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MOSFET-based Buck Converter Turn-on Waveforms



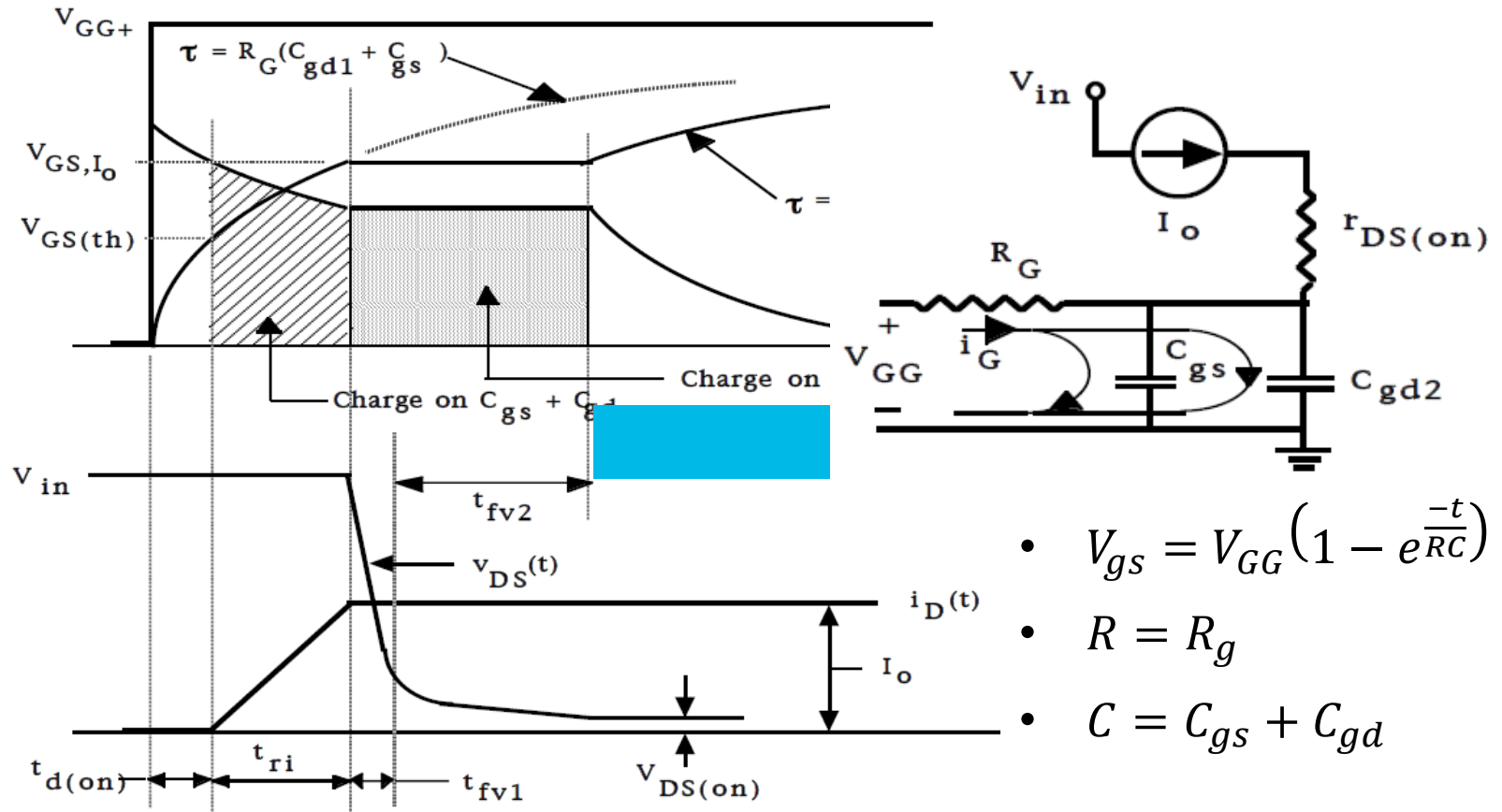
• Equivalent circuit during t_{fv1} .



- $V_{gs} = V_{GP}$
- $i_g = \frac{V_{GG} - V_{GP}}{R_g} = C_{gd} \frac{dV_{ds}}{dt}$

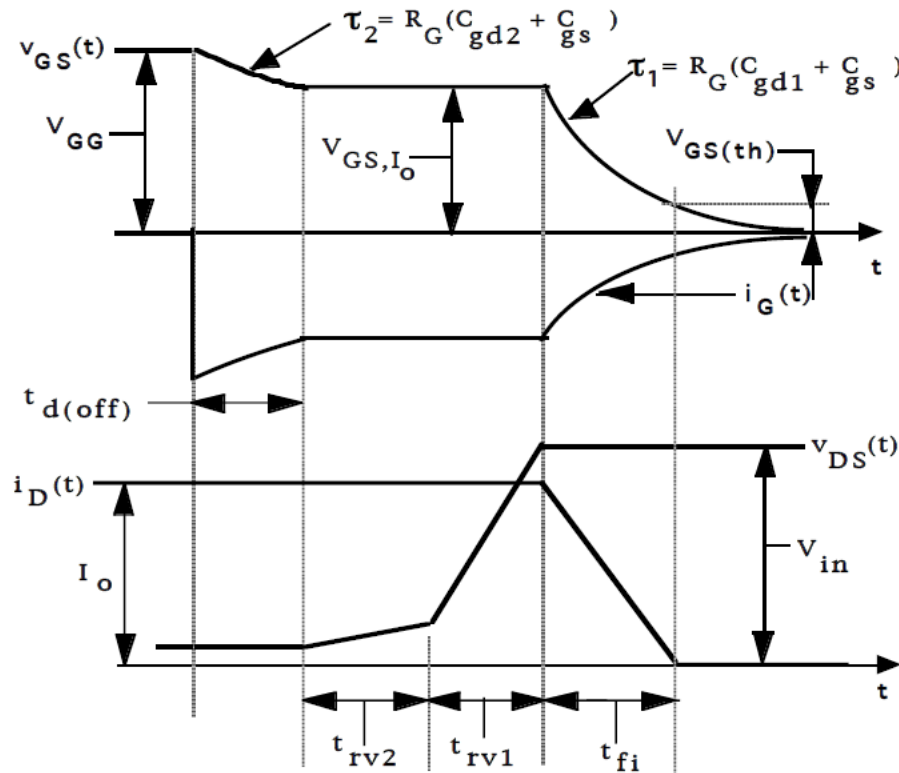
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MOSFET-based Buck Converter Turn-on Waveforms



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MOSFET-based Buck Converter Turn-off Waveforms



- Assume ideal free-wheeling diode.
- Essentially the inverse of the turn-on process.
- Model quantitatively using the same equivalent circuits as for turn-on. Simply use correct driving voltages and initial conditions

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MOSFET data sheet



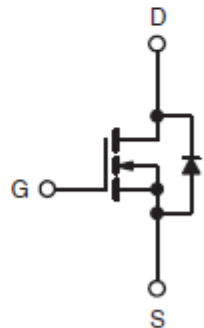
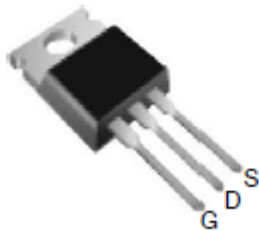
IRF540, SiHF540

Vishay Siliconix

Power MOSFET

PRODUCT SUMMARY	
V_{DS} (V)	100
$R_{DS(on)}$ (Ω)	$V_{GS} = 10\text{ V}$ 0.077
Q_g (Max.) (nC)	72
Q_{gs} (nC)	11
Q_{gd} (nC)	32
Configuration	Single

TO-220AB

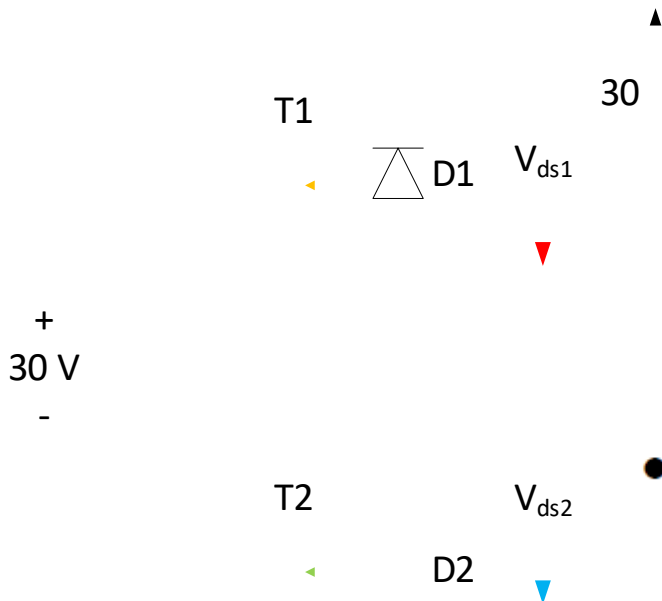


N-Channel MOSFET

Definitions of device capacitances.

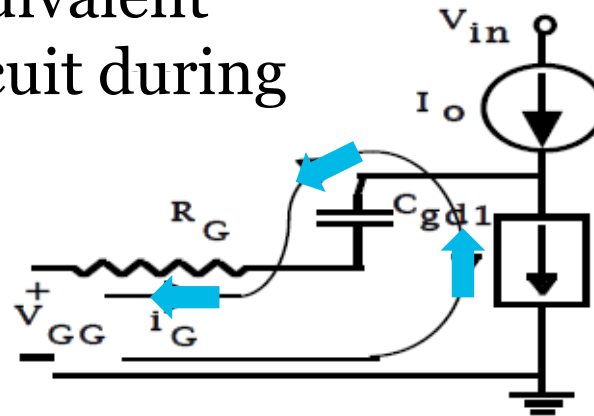
- $C_{iss} = C_{GS} + C_{GD}$, C_{DS} shorted
- $C_{rss} = C_{GD}$
- $C_{oss} = C_{DS} + C_{GD}$

MOSFET T1 turn-on. Disturbance on T2 ??



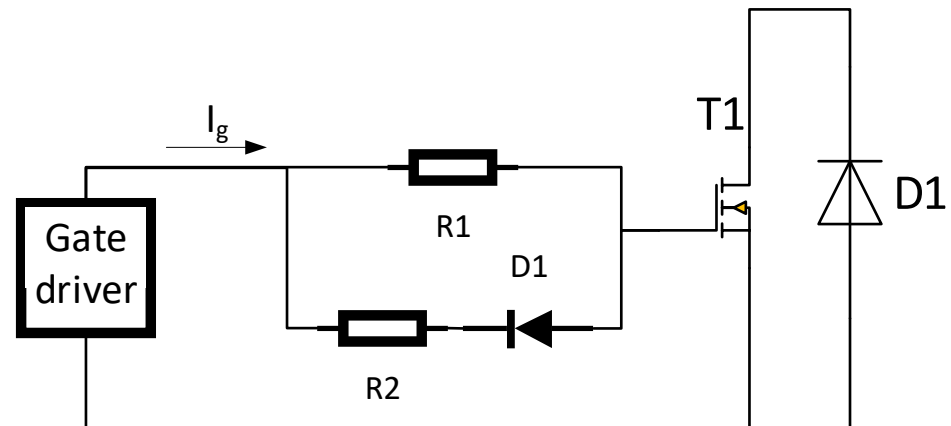
- $V_{GG2} = 0$
- $i_{g2} = C_{gd} \frac{dV_{ds}}{dt}$
- $V_{gs2} = V_{GG2} + R_g i_{g2}$
- $V_{gs2} > V_{gs(th)}$
- **T2 TURN-ON**

• Equivalent circuit during t_{rv1}

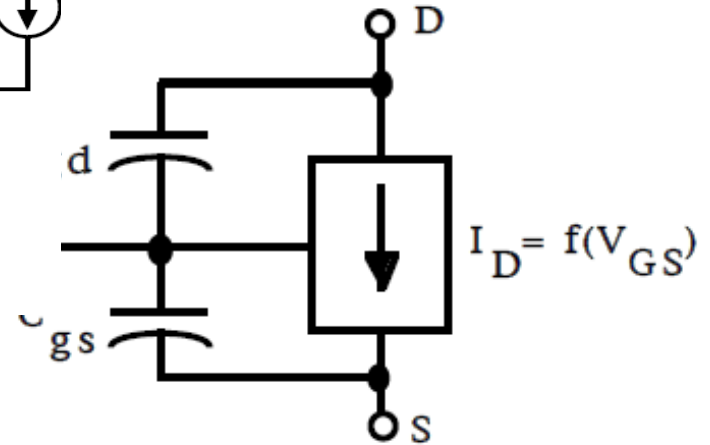
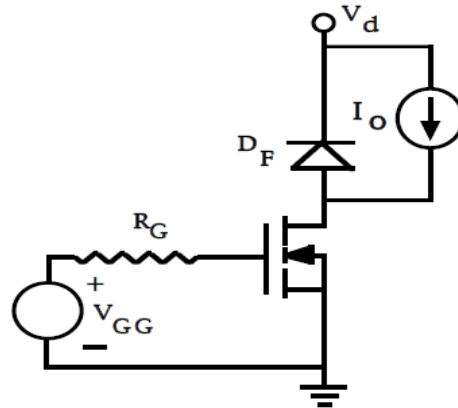


Gate resistance control

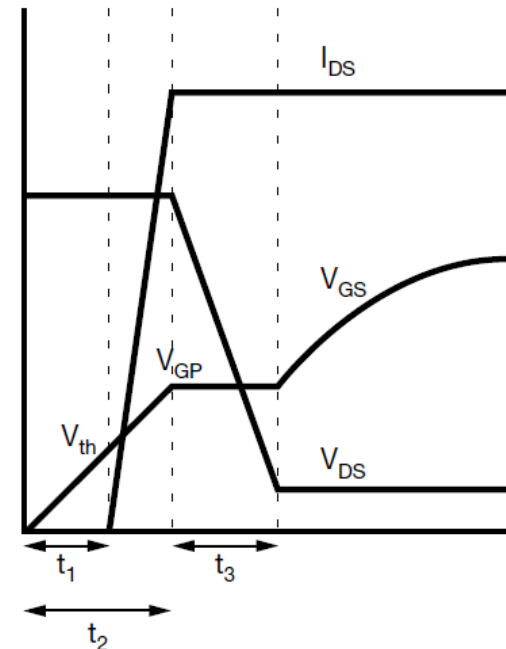
- Separate $R_{g(\text{on})}=R1$ and $R_{g(\text{off})}=R2$
- Diode D1 makes R1 active during turn-on and R2 active during turn-off
 $R2 \ll R1$
- Reduced $R_{g(\text{off})}$ to prevent parasitic turn-on at high dv/dt



5-100

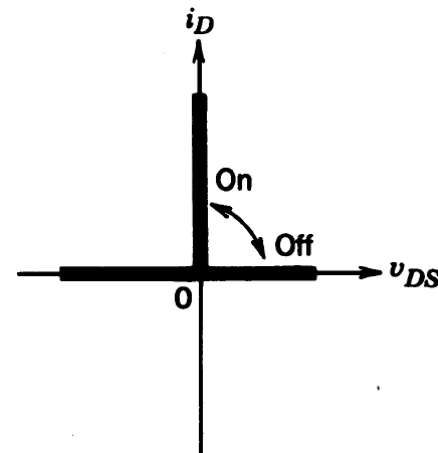
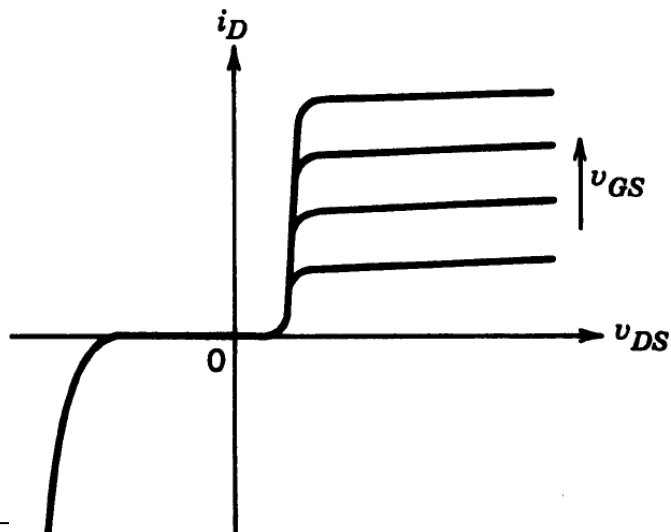
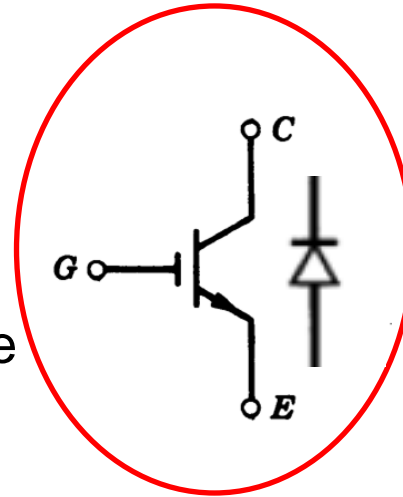


- For a step-down converter the dV_{DS}/dt of a MOSFET during turn-on is defined by V_d (assume $V_{dson}=0$) and t_{fv} .
- $V_{ds} = 100\text{ V}$, $t_{fv} = t_3 = 200\text{ ns}$
- The gate-drain capacitance, $C_{gd} = 120\text{ pF}$. The miller plateau voltage $V_{GP} = 4\text{ V}$
- Calculate the gate resistance, R_G for a gate drive with $V_{GG} = 10\text{ V}$ which gives a dV_{DS}/dt as specified.



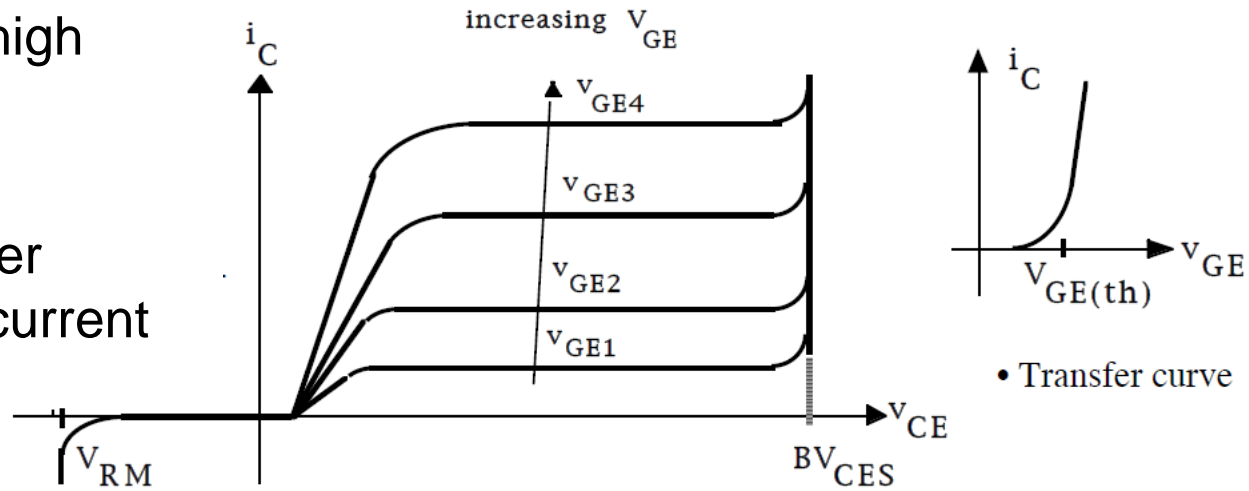
Insulated gate bipolar (IGBT)

- High input impedance
- Small on-state voltage
- Large blocking voltage
- Combined with anti-parallel diode

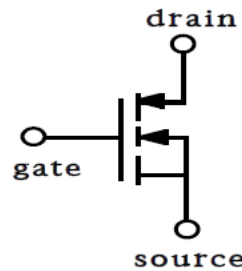
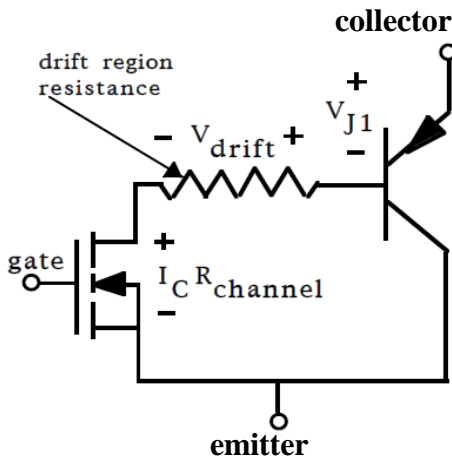


Insulated gate bipolar (IGBT) implementation

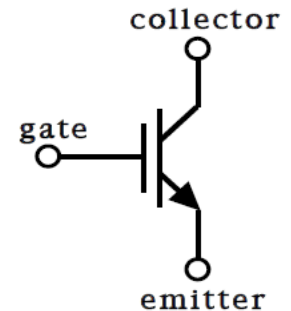
- Bipolar carrier conduction (electron & holes)
low voltage drop at high current
- PN-junction in PNP transistor gives higher voltage drop at low current



• Transfer curve



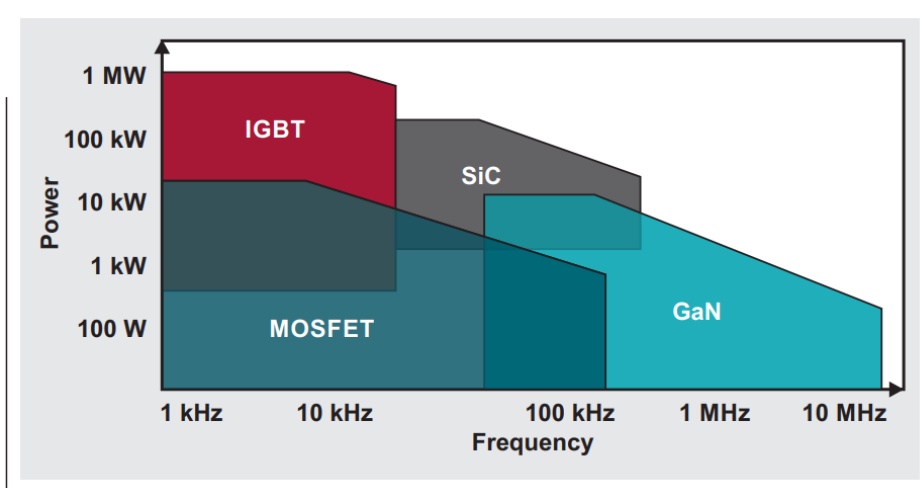
• N-channel IGBT circuit symbols



Semiconductor materials

- **Silicon**
MOSFET & IGBT
- **Silicon Carbide**
MOSFET
- **Gallium Nitride**
MOSFET, HEMT

Parameter	GaN	SiC	Si
Electron mobility ($\text{cm}^2/\text{V}\cdot\text{s}$)	1800	900	1400
Energy gap (eV)	3.5	3.26	1.12
Breakdown electric field (MV/cm)	3.3	3	0.3
Thermal conductivity ($\text{W}/\text{cm}\cdot\text{K}$)	1.3	4.9	1.5
Saturation drift velocity (Mcm/s)	27	27	10



Source: Wide-bandgap semiconductors: Performance and benefits of GaN versus SiC, Analog Design Journal, Texas Instruments 2020

Lecture 4

Thermal management

Cooling requirement motivation

- Component failure rate increase with temperature increase
- Capacitors
 - Electrolyte evaporate reate increase with temperature
- Magnetic components
 - Losses in magnetic components increase when $T > 100$ degrees
 - Winding insulation degrades when $T > 100$ degrees
- Semiconductors
 - Breakdown voltage decrease
 - Leakage current and switching time increases
 - Power sharing problems when parallel or serial devices

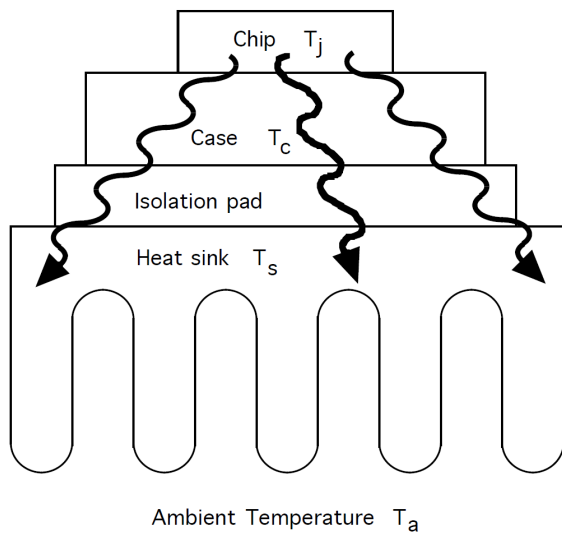
Heat sinks

- Different shapes and material
- Based on convection and radiation
 - Natural convection
 - Forced-air convection
- Examples: Computers, trains,



Thermal model with electric analogy

- Power corresponds to current,
- Temperature corresponds to voltage,
- Thermal resistance R_{Θ} (or R_{th}) corresponds to ohmic resistance



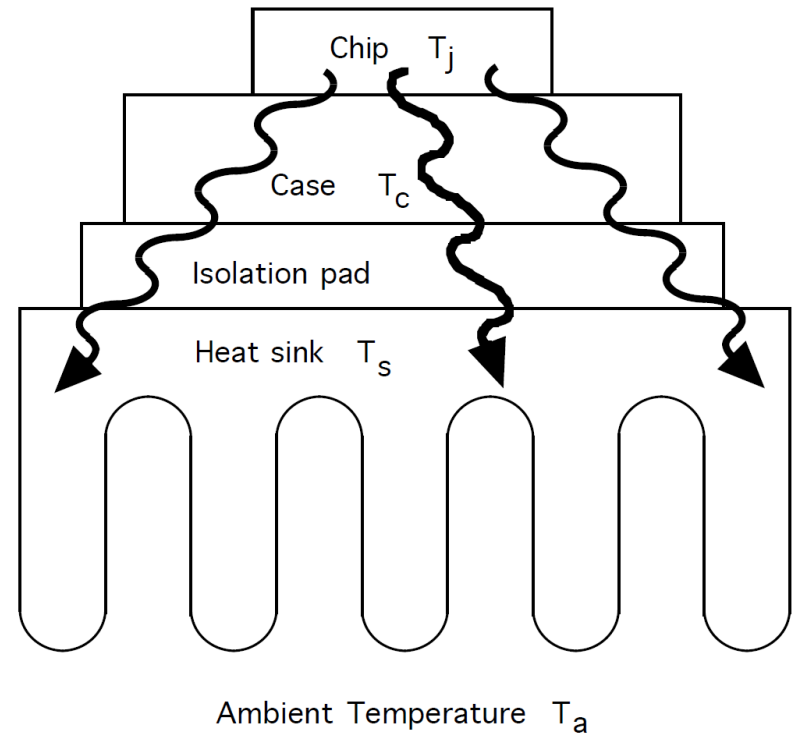
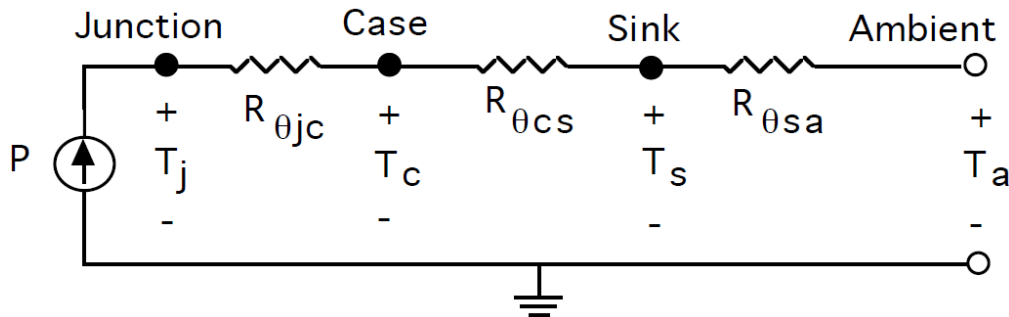
$$\Delta T = P \cdot R_{\Theta} \text{ [K/W]}$$

$$R_{\Theta} = \frac{\Delta T}{P} \text{ [K/W]}$$

Multiple layer structure model

- Typical cooling setup
 - Different sizes and materials
- Electric model of the power transfer from power source to the environment

$$T_j = T_c + \Delta T_{jc} = T_c + P \cdot R_{\theta,jc}$$

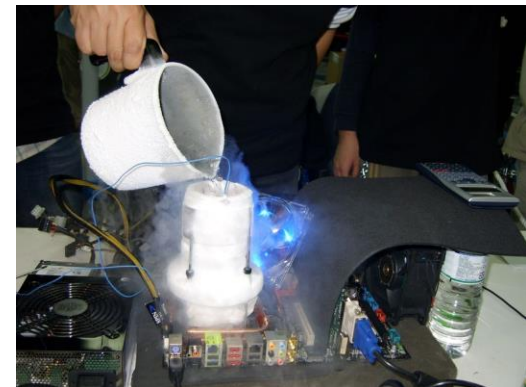


29-6

- A MOSFET used in a step-down converter has an on-state loss of 50 W and a switching loss given by $10^{-3} f_s$ (in watts) where f_s is the switching frequency in hertz.
- The junction-to-case thermal resistance $R_{th,jc}$ is 1 K/W and the maximum junction temperature $T_{j,max}$ is 150°C.
- Assuming the case temperature is 50°C, estimate the maximum allowable switching frequency.

Other cooling approaches

- Liquid cooling
 - Allow larger heatsinks, placed away from power source
- Thermal towers, heatpipes
 - Similar principle as in a refrigerator (phase shifting)
 - Connect a larger heatsink without large thermal resistance
- Liquid nitrogen
 - Force temperature down below T_a
 - Expensive
 - Water condensation problems
 - Material stress problems



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